

'Enhancing Patient Care Through Operational Efficiency'







AUTONOMOUS MOBILE INDUSTRIAL ROBOT



INFRASTRUCTURE
FREE NATURAL NAVIGATION



MODULAR DESIGN FOR EXECUTING MULTIPLE APPLICATIONS



FLEXIBLE & SAFE FOR COLLABORATIVE OPERATION



MACHINE LEARNING ENABLED FOR TRULY AUTONOMOUS OPERATIONS



CLOUD BASED ANALYTICS FOR REAL-TIME INSIGHTS



QUICK RETURN ON INVESTMENT



HANDLE LOADS IN ALL SHAPES & SIZES (PALLETS/RACKS/TOTES/TROLLEYS)



APPLICABLE FOR GREENFIELD SITE AND BROWNFIELD SITE

OPTIMIZING YOUR INTRALOGISTICS OPERATIONS





SCISSOR LIFT



UNIT LOAD



TROLLEY TOWING



CONVEYOR BED

PRODUCT SPECIFICATIONS

DESCRIPTION	AMIR 100	AMIR 500	AMIR 1500
Dimensions			
Length Width Height Height with Lifter Ground clearance	850 mm 550 mm 368 mm 500mm 55 mm	1100 mm 750 mm 410 mm 610 mm 35 mm	1740 mm 1140 mm 380mm 550 mm 25 mm
Weight (without load) Load surface Wheel diameter	100 kg 600 x 800 mm Drive wheel: 200 mm Castor	250 kg 600 x 830 mm Drive wheel: 210 mm Castor	410 kg 1270 mm x 770 mm Drive wheel: 200 mm. Castor
wheel: 100 mm wheel: 100 mm wheel: 150 mm Payload			
Robot payload Towing capacity	100 KG 300 kg	500 KG 750 kg	1500 KG 2000 Kg
Speed and Performance			
Battery Running time		8 Hours	
Maximum speed	forwards: 1.1 m/s (4 km/h) backwards: 1.1 m/s (4 km/h)	forwards: 1.25 m/s (4.5 km/h) backwards: 1.25 m/s (4.5 km/h)	forwards: 1.5 m/s (5.4 km/h) backwards: 1.5 m/s (5.4 km/h)
Acceleration De-Acceleration Maximum incline		0.2 m/s^2 (full payload, flat surface) 0.2 m/s^2 (full payload, flat surface) 5% Incline (with payload)	
Turning circle Dia (On the spot 1	T urn) 1020 mm	1400 mm	2050 mm
Minimum width, door Minimum width, passage Minimum width, two robots pas Precision docking	1000 mm 1000 mm 2200 mm +/-20 mm +/-50 mm of position,	1450 mm 1450 mm 2500 mm +/-30 mm +/-50 mm of position,	1850 mm 1850 mm 3500 mm +/-30 mm +/-50 mm of position,
Stopping accuracy	+/-20 mm to docking marker	+/-30 mm to docking marker	+/-30 mm to docking marker
Power			
Battery Charging Time External charger Battery Charging Cycle	Li-ion 24 V , 54 Ah up to 3.5 hours (0-80%: 2.5 hours) Input: 200-240 V ac, 50-60 Hz / Output: 24 V, max 18 A Minimum 1200 cycles	LiFPo 24 V, 80 Ah up to 4 hours (0-80%: 3 hours) Input: 200-240 V ac, 50-60 Hz / Output: 24 V Minimum 1500 cycles	Li-ion, 48 V, 76.5 Ah upto 5.5 hours, (0-80%: 4 hours) Input: 100-230 V ac, 50-60 Hz / Output: 48 V Minimum 1200 cycles
Ambient temperature rang	rige Environment +5°C to 50°C (humidity 10-95% non-condensing) IP 21		
WiFi I/Os	Commun	nication Dual-band wireless AC/G/N/B Ethernet and USB	
Safety Safety			
Safety System	2D Laser Scanner, Ultrasonic Sensor, Optional Contact Type Safety sensor, 2 Emergency Stop Butto	2D safety Laser Scanners, Contact Type Safety Bumper, Safety PLC, 2 ons Emergency Stop Buttons	2D Safety Laser Scanners, Contact Type Safety Bumper, Safety PLC ,4 Emergency Stop Buttons

With Adaptable Design of Novus Carry any specific application requirement can be easily met by using different Auxiliary Attachments

Navigation

2D LiDAR (Natural Navigation)

Navigation Sensor

NOVUS ANALYTICS

Take Your Producitivity to Next Level

NOVUS ANALYTICS is a web based application monitoring all the Novus Family AMIRs in Real Time. With the use of Machin Learning & other Data Analytics Tools, this application logs, consolidates and presents data to user in such a way so that s(he) can improve processes and increase the productivity.





EMPOWER C-SUITE

Location Trip Matrix



IMPROVE RELIABILITY



SPEED OPERATIONS



MONITOR & REACT





Pa

Location of all the vehicles

Status of individual vehicle



Fault List



Alarm Type



Idling Time Report



Cycle Time Report



Overall Equipment Efficiency



Process Performance

INTELLIGENT SOLUTION FOR FLEXIBLE OPERATIONS



Unlike AGV, no infrastructure change. Uses LIDAR to Navigate



Avoids obstacle & finds the next best



It routes to the optimum path using advanced analytics



Easily accustomed for any change in lauout



Easy shifting to new facility, due to ease of installation



Easy integration with ERP/WMS/FMS, due to presence of on-board computer

MOVING TOWARDS INDUSTRY 4.0

EQUIPMENT LEVEL

Material movement through **Autonomous Mobile Industrial** Robots (AMIR)

Human dependency for Dispatching & Sequencing of AMIR







Reduced No Product 24 x 7 Head Count Damage Operation

> Reduced **Labor Cost**



PROCESS LEVEL

AMIRs powered with Fleet Management & Analytics Software

Data logging, reporting and forecast related to AMIR behavior

Time

Logistics







Performance Analysis

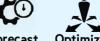
Reduced Logistics & **Operational Cost**

PLANT LEVEL

Integration of Logistics & **Production Process with IOT devices**

Monitoring OEE including AMIR & related affiliate equipments





Increased Revenue





Identify &



IMPACT

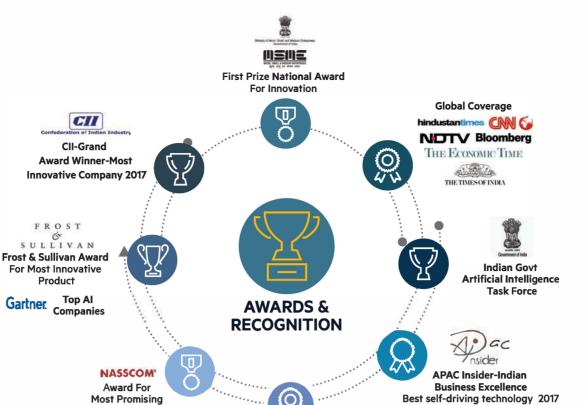
LEVEL OF

AUTOMATION

PHASE

ASPECTS

GAINS



South Asia Innovation Award
Best self-driving
technology

COMPANY OVERVIEW

CLIENTELE

Designs, developes & sells Autonomous and driver-assistance software and systems for commercial automotive as well as industrial applications

Emerging Companies 2016

- 250+ employees with more than 120 R&D engineers including 34 machine learning and computer vision experts
- First mover with 90% market share in India 350+ autonomous & assistive systems including 150+ industrial vehicles
- Automotive applications: provides products that enable driver awareness as well as partial, conditional and full autonomy
- Industrial applications: provides autonomous mobile robots for end-to-end logistics in manufacturing & warehousing
- Core competencies include machine learning & sensor fusion, computer vision technology, software & embedded system design, mechanical design and motion planning & control
- Already built and sold up to L4 autonomous & assistive systems
- 50+ Patent Portfolio across US, EU, India & SA











































